

Robo3DText – Robot-guided multifunctional 3D printing on textile substrates

Problem / Motivation

- 3D printing on textiles has mainly been done on planar surfaces
- Partial finishing or printing on finished, three-dimensional, draped or near-net-shape textiles is very limited
- More complex printed structures can only be achieved with the help of elaborate support structures
- The aim is the adaptation of the print head to a robot system for more degrees of freedom in the movement of the print head

Solution

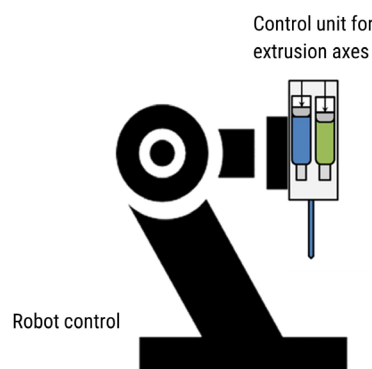
- Adaptation of printing materials to the process focusing on paste-like materials based on biobased raw materials (LAM process)
- Use of a 2-component print head to combine two print materials with variable mixing ratios
- Control technology implementation of the 2K print head on a 6-axis industrial robot system for applying the developed formulations to non-planar components
- Partial functionalisation of textile substrates close to the final contour

Project Start

07/2024

Project Partner

currently none,
open for enquiries



Schematic representation of a 2K print head mounted on a robotic system

Acknowledgement

We would like to thank the Federal Ministry for Economic Affairs and Climate Action for funding the research project Robo3DText (Reg. No. 49MF240012) within the funding programme "FuE-Förderung gemeinnütziger externer Industrieforschungseinrichtungen – Innovationskompetenz (INNO-KOM) – Marktorientierte Forschung und Entwicklung (MF)".

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Supported by:



on the basis of a decision
by the German Bundestag